UFYS2010: Radio astronomy instrumentation and interferometry

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Based partly on 'Essential radio astronomy' from http://www.cv.nrao.edu/course/astr534/Interferometers1.html by J. J. Condon and S. M. Ransom.

Recap from lecture 6

History

Two-element monochromatic interferometer

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Recap from lecture 6



Recap: Poincaré sphere and Stokes parameters





If 2Ψ is interpreted as longitude and 2χ as latitude on a sphere with a radius of S_0 , all polarization states can be expressed on a surface of a sphere. The positions on equator correspond to linear polarization, north pole right hand circular and south pole left hand circular polarization. The axes correspond to *Stokes parameters*.

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Recap: Stokes parameters II

The previous definitions can be used to express the polarization state of a wave exactly but they do not correspond directly to observable quantities. By expressing the parameters using field vectors and their phase shift, we get:

$$S_{0} = I = E_{1}^{2} + E_{2}^{2}$$

$$S_{1} = Q = E_{1}^{2} - E_{2}^{2}$$

$$S_{2} = U = 2E_{1}E_{2}\cos\delta$$

$$S_{3} = V = 2E_{1}E_{2}\sin\delta$$
(1)

Special cases:

- ▶ Right-handed circular polarization: I = V = S and Q = U = 0
- ▶ Left-handed circular polarization: I = S, V = -S and Q = U = 0
- Linear polarization: I = S, V = 0, $Q = I \cos 2\Psi$ and $U = I \sin 2\Psi$

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Polarimetric observations give information of the magnetic field strength and direction and also of electron (charge) density. This is due to Faraday effect where the electric vector polarization angle (EVPA) of a linearly polarized wave rotates when it travels trough a medium with plasma and magnetic field:

$$\chi^{\rm lin}(\lambda) = \chi_0^{\rm lin} + {\rm RM} \cdot \lambda^2, \qquad (2)$$

where

$$\mathrm{RM} = 0.81 \int_{\mathrm{source}}^{\mathrm{observer}} n_e \overrightarrow{B} \cdot \mathrm{d} \overrightarrow{l}.$$
 (3)

 χ_0^{lin} is the original EVPA, RM is *rotation measure*, n_e is electron density (cm^{-3} , B is magnetic field strength (μG), and I is travelled distance in parsec.

(Rohlfs et al. book uses χ in different context, because of this χ^{lin} is used here for EVPA)

THE QUEST FOR RESOLUTION

Resolution = Observing wavelength / Telescope diameter					
Angular	Optical (5000A)			Radio (4cm)	
Resolution	Diameter	Instrument		Diameter	Instrument
1'	2mm	Eye		140m	GBT+
1″	10cm	Amateur Telescope		8km	VLA-B
0.″05	2m	HST		160km	MERLIN
0.″001	100m	Interferometer		8200km	VLBI
Atmosphere gives 1" limit without corrections which are easiest in radio					
Jupiter and Io as seen from Earth					
1 arcmin 1 ar		esec 0.05 ares		sec 0.0	001 arcsec
			6	0	0

From Walker (2002)

EM frequency-resolution space



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VLBI (Very Long Baseline Interferometry)



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Recap from lecture 6

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How it all begun (here and there)



Sir Martin Ryle (1918 - 1984)



Jorma J. Riihimaa (1933 - 2011)



K.39. Teekkari J.J. Riihimaa etuvahvistinta virittämässä.

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K. 36. "Jätepuuantenni". Toinen kahdesta neljän kokoaaltodipolin ryhmästä Viikin koetilan alueella. Taustalla "työnjohtajan koppi". (Heinäkuu 1953)

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A new radio interferometer and its application to the observation of weak radio stars

By M. Ryle

(Communicated by Sir Lawrence Bragg, F.R.S.—Received 19 June 1951— Revised 10 October 1951)

A new type of radio interferometer has been developed which has a number of important advantages over earlier systems. Its use enables the radiation from a weak 'point' source such as a radio star to be recorded independently of the radiation of much greater intensity from an extended source. It is therefore possible to use a very much greater recorder sensitivity than with earlier methods. It is, in addition, possible to use pre-amplifiers at the aerials, and the resolving power which may be used is therefore not restricted by attenuation in the aerial cables.

Besides improved sensitivity, the new system has a number of other advantages, particularly for the accurate determination of the position of a radio source. Unlike earlier systems the accuracy of position finding is not seriously affected by rapid variations in the intensity of the radiation. It also has important applications to the measurement of the angular diameter and polarization of a weak source of radiation.

The new system has been used on wave-lengths of 1.4, 3.7, 6.7 and 8 m for the detection and accurate location of radio stars, and for the investigation of the scintillation of radio stars. It has also been used in a number of special experiments on the radiation from the sun. The results which have been obtained in these experiments have confirmed the advantages predicted analytically.



K.43. Ensimmäinen rekisteröinti Cass A:n ohikulusta 2-3.8.1953. (81.5 MHz)

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- ► First fringes by Riihimaa (OH2PX,OH8PX) in 1953
- 1973 Riihimaa started decametric observations with a two-LPDA interferometer in Oulu
- 1979 First tests in Mets"ahovi with the 13.7m telescope at 5 GHz
- 1991 First observations at 22 GHz with Finnish-built equipment
- ▶ 1995 First mm-VLBI at 86 GHz
- > 2001 First 2mm (150 GHz) observations
- Fast development of eVLBI ({www.metsahovi.fi})

e- VLBI:

connecting remote telescopes in real-time



Huib Jan van Langevelde Joint Institute for VLBI in Europe Sterrewacht Leiden

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Interferometry

Interferometry is based on correlation (multiplication and averaging) of signals from two radio telescopes.



- One pair of telescopes gives one baseline and one visibility in the uv-plane.
- Correlating signals from multiple telescopes pairwise gives visibilities from different baselines.
- ► N telescopes give N(N 1)/2 independent baselines and visibilities.

Geometry of a two-element interferometer



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 \vec{b} = baseline vector, \hat{s} = unit vector to source, $\tau_{g} = \vec{b} \cdot \hat{s}/c$ = geometric delay between signals.

Signals from antennas



At frequency $u = \omega/(2\pi)$ the signals from antennas are

$$V_1 = V \cos[\omega(t - \tau_g)]$$
 and $V_2 = V \cos(\omega t)$. (4)

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Correlation



After multiplication the product is averaged with a timescale of typically seconds), so that the term $\cos(2\omega t - \omega \tau_g)$ averages out.

$$V_1 V_2 = V^2 \cos(\omega t) \cos[\omega(t - \tau_g)] = \left(\frac{V^2}{2}\right) [\cos(2\omega t - \omega \tau_g) + \cos(\omega \tau_g)]$$
(5)

Averaged multiplication = correlation



The averaged product i.e. correlation is

$$R = \langle V_1 V_2 \rangle = \left(\frac{V^2}{2}\right) \cos(\omega \tau_{\rm g}) \,.$$
(6)

Output amplitude $V^2/2$ is proportional to the point-source flux density multiplied by the geometric mean of the telescope effective areas.

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Fringes



The correlation result $\left(\frac{V^2}{2}\right)\cos(\omega\tau_g)$ varies sinusoidally because the source direction is slowly changing (earth rotation). These sinusoids are called *fringes. Fringe phase* is

$$\phi = \omega \tau_{\rm g} = \frac{\omega}{c} b \cos \theta \tag{7}$$

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and depends on direction as follows:

$$\frac{d\phi}{d\theta} = \frac{\omega}{c}b\sin\theta = 2\pi\left(\frac{b\sin\theta}{\lambda}\right).$$
 (8)

Fringes are tapered by the primary beam if telescopes are not tracking the source.

Fringe phase and source position



$$\frac{d\phi}{d\theta} = \frac{\omega}{c} b \sin \theta = 2\pi \left(\frac{b \sin \theta}{\lambda}\right) \quad (9)$$

One fringe period $\Delta \phi = 2\pi$ corresponds to an angular change of $\Delta \theta = \lambda / (b \sin \theta).$

Because of this, it is very sensitive measure of source position if the projected baseline $b \sin \theta$ is very long in wavelengths.

Fringe phase does not depend on telescope direction i.e. tracking errors but depends only on time. Interferomteres can determine positions with better accuracy than any other methods. Absolute positions in milliarcseconds and relative down to tens of

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Example: Parallax and proper motion of T Tau Sb



The VLBA was used to measure the parallax and proper motion of the radio star T Tau Sb. The measured parallax $\Pi = 6.82 \pm 0.03$ milli-arcsec implies a distance $D = 146.7 \pm 0.6$ pc (Loinard et al. 2007, ApJ, 671, 546), an improvement by nearly two orders of magnitude over the distance $D = 177^{+68}_{-39}$ pc obtained by the Hipparcos astrometry satellite.



Isotropic antenna elements would fill the sky with a sinusoid response. Individual responses of (real world) directive antenna elements are multiplied with the sinusoid, result is a 'sinusoid pulse' pattern.

One baseline is sensitive to only one spatial frequency $(b \sin \theta / \lambda)$. To improve response, more Fourier components are needed.

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Fourier spatial frequencies and synthesized beam



An interferometer with N antennas contains N(N-1)/2 pairs of antennas i.e. baselines These cases have

- one baseline b
- three baselines b, b/3, 2b/3
- six baselines b, b/6, 2b/6, 3b/6, 4b/6, 5b/6

When the number of **unique** baselines are increased, the synthesized beam approaches Gaussian with angular resolution $\approx \lambda/b$.